

JPL-Caltech Virtual Summer School

# Big Data Analytics

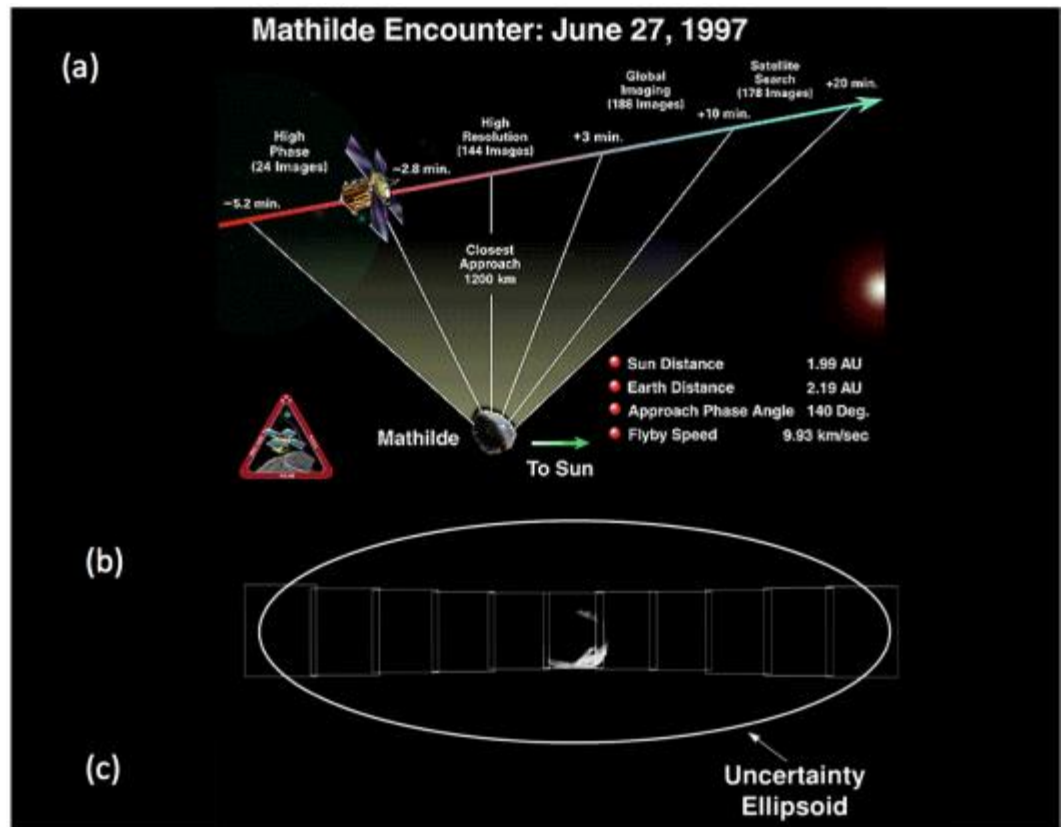


September 2 – 12, 2014

Thomas Fuchs (JPL, Caltech)  
Application: Flyby Science

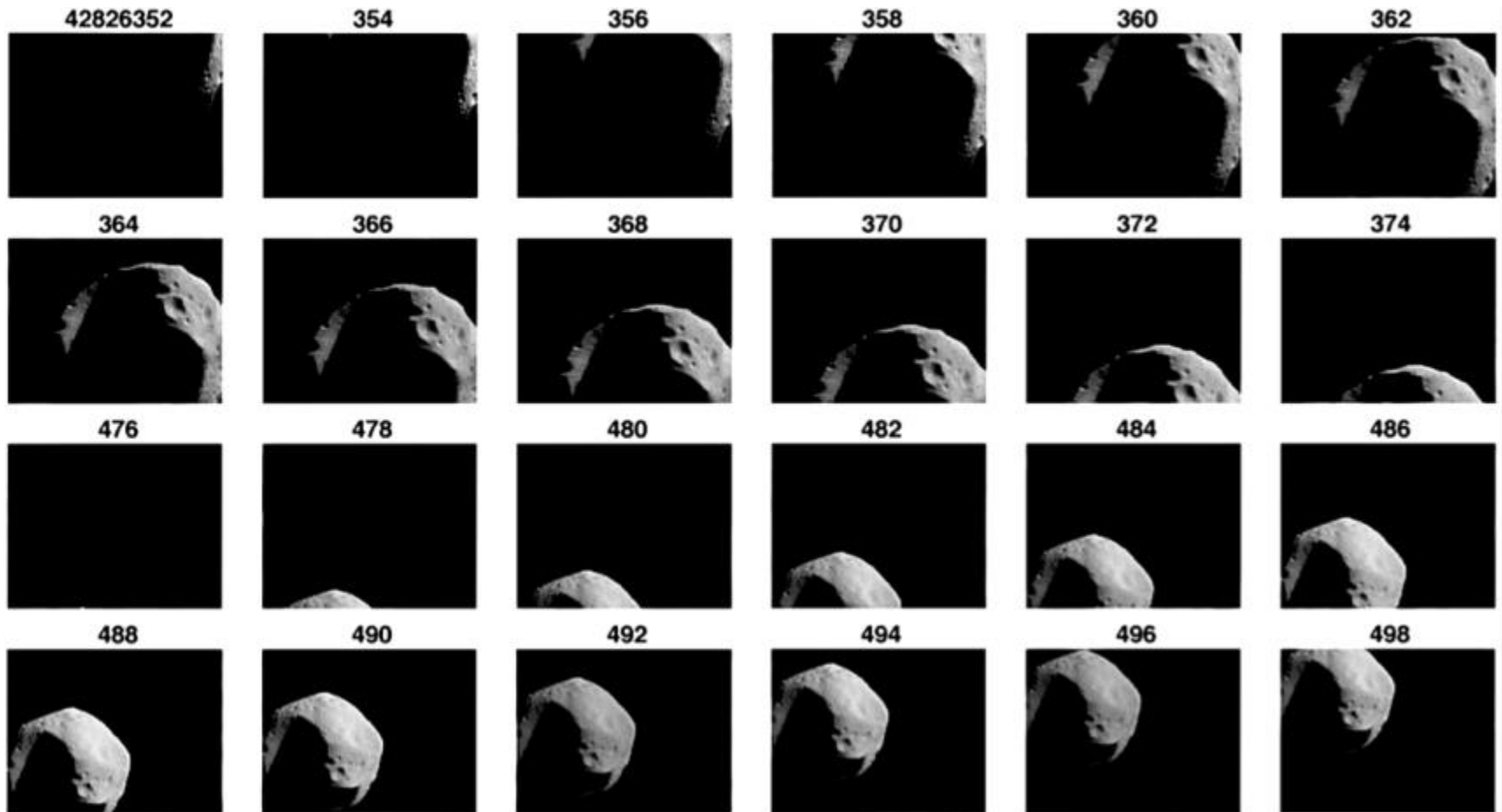
# Flyby science is hard!

- Targets have diverse morphologies, compositions
- Target locations are not known in advance
- Closest approach may pass quickly (sub-hour timescales)
- Geometry and illumination constraints
- Features of interest are highly localized



J. Veverka and 16 co authors. Near's flyby of 253 mathilde: Images of a C asteroid. Science, 278:2109, 1997.

# Flyby science (typical)



J. Veverka and 16 co authors. Near's flyby of 253 mathilde: Images of a C asteroid. Science, 278:2109, 1997.



# Status Quo: respond in days



# Onboard analysis: respond in minutes



Light  
time  
delay



Processing  
and analysis



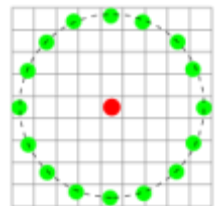
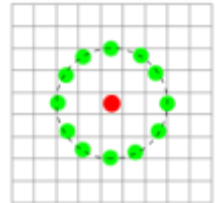
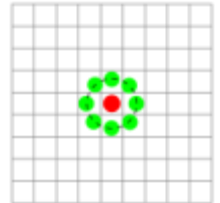
Replanning and  
sequencing

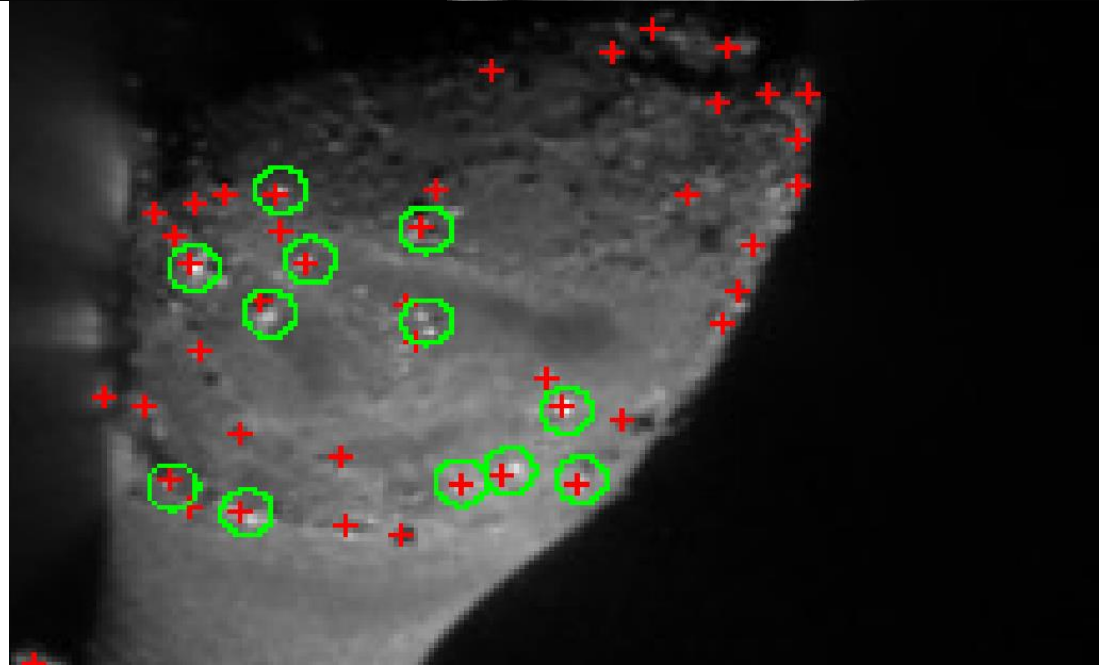
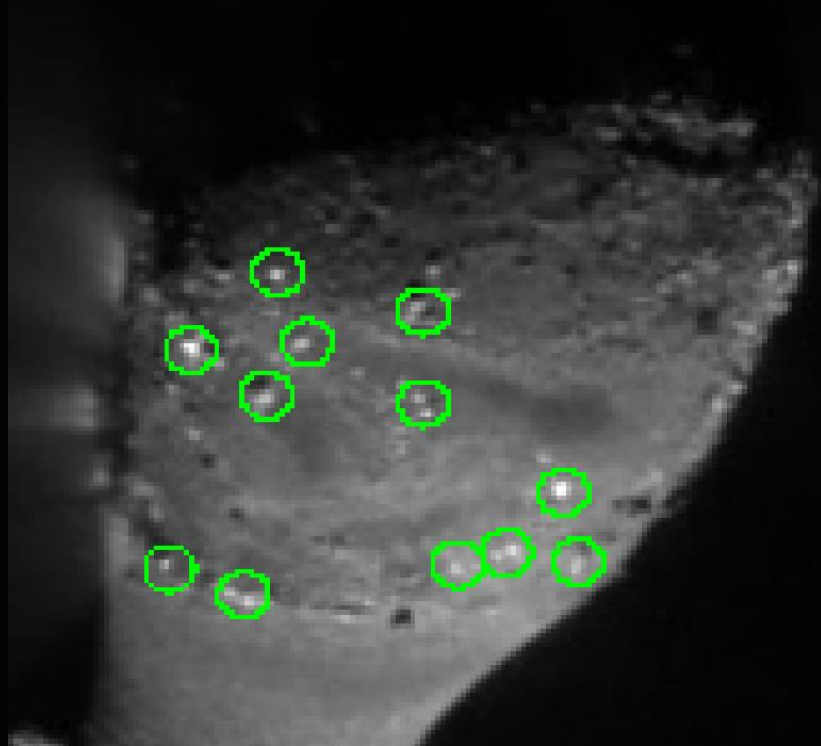
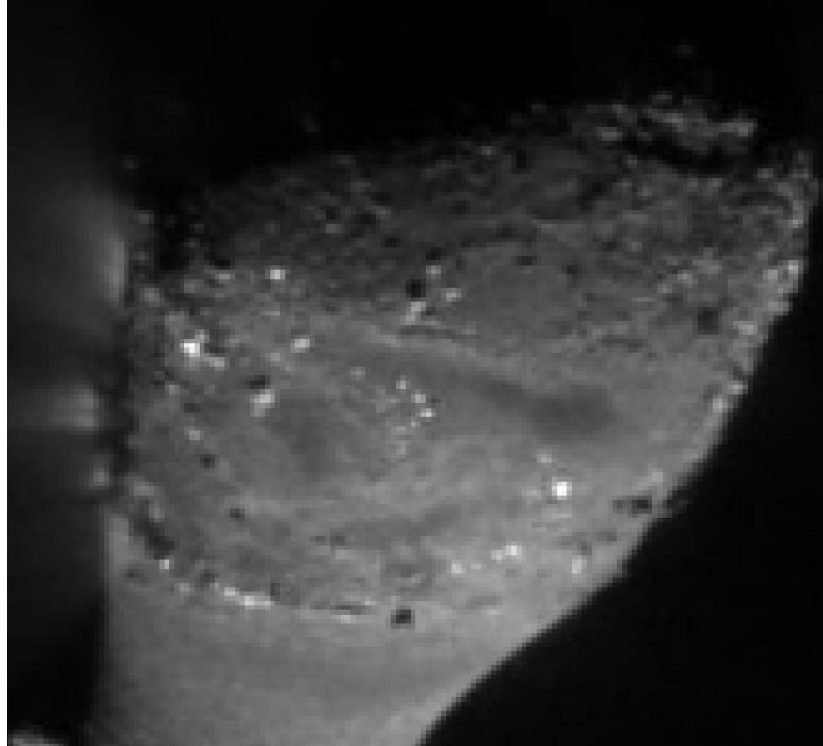
Rosetta graphic courtesy NASA / ESA / US.  
Rosetta  
DSN image courtesy NASA / Caltech / JPL



# Feature Extraction

- **Local Binary Pattern (LBP)** for texture description
- Image based binary and intensity weighted **Mean Shift** for mode detection
- Edge preserving constant time **Median Filter**
- **Integral Images** for Haar features, etc.
- 3D color histogram **features**, gradient histograms, census transform, etc.
- **Color** conversion: RGB, HSV, LAB, norm. col, etc.



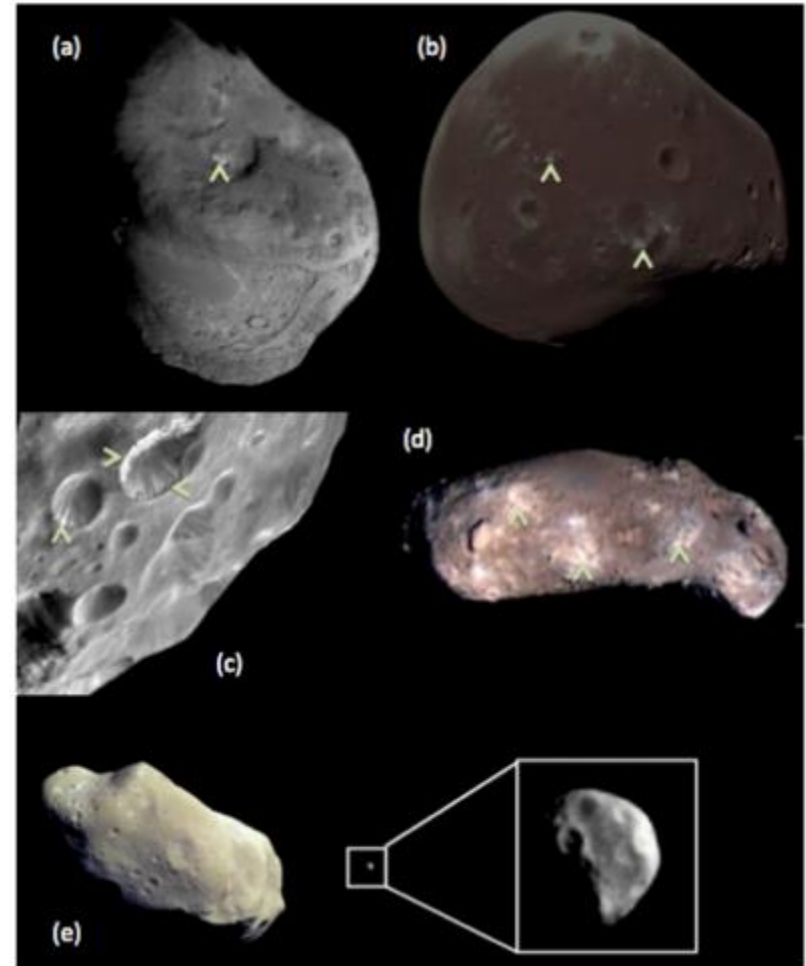


# Our focus: Pattern recognition for surface features

Indicate fresh subsurface material uncovered by impacts or wasting events

Reveals interior composition with stronger and more unique spectral signatures

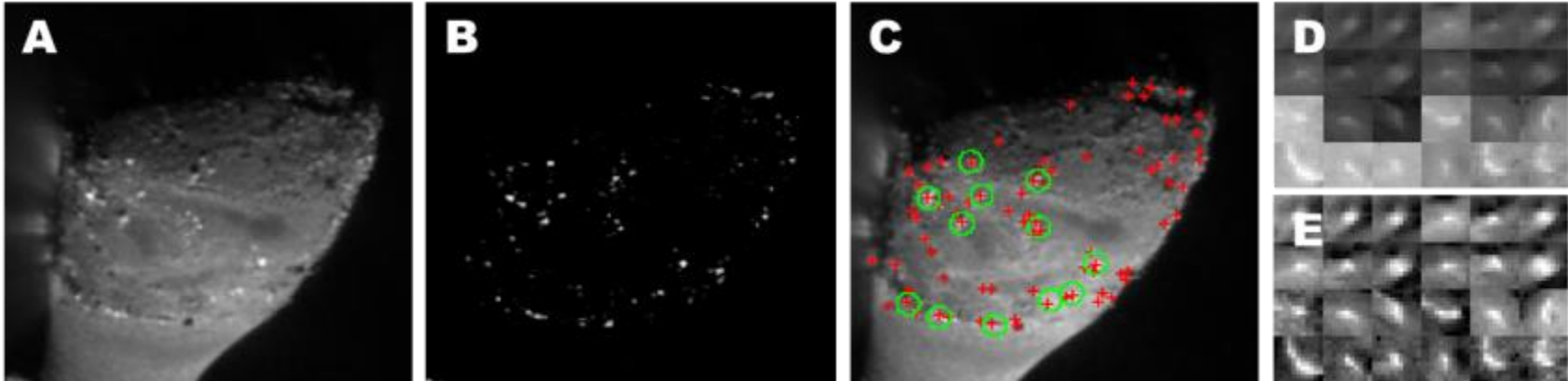
A good candidate for followup measurements



Images: various sources (NASA, JAXA) available on request



# Pattern recognition approach



Original (Hartley 2)

Median filtering  
finds high-albedo  
spots

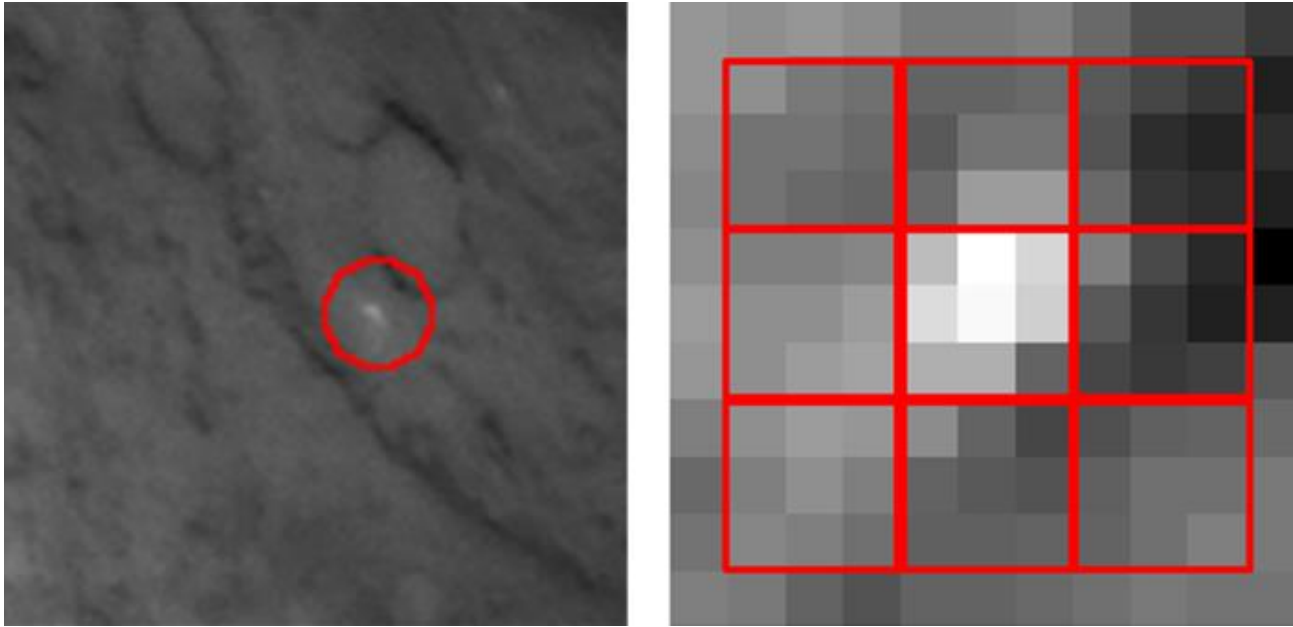
Random forest  
classification

Extracted  
image patches

- Median filtering finds candidate spots which are then filtered by a random forest classifier.
- Classification only runs on candidate pixels, making runtime amenable to a flight processor such as a Rad750-class device



# Surface feature attributes

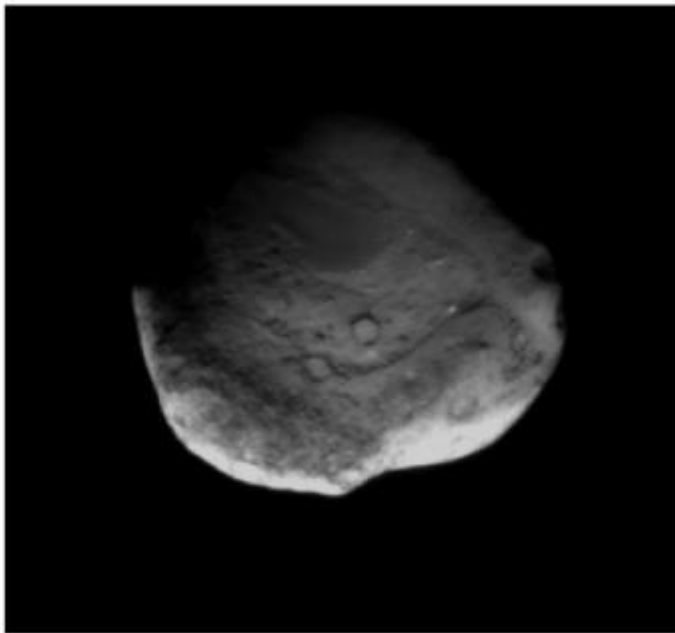


- Calculate attributes from  $11 \times 11$  pixel image patches at the locations of each candidate.
- Include intensity values and general image statistics, gray value and gradient histograms, local binary patterns (LBP), etc.
- Normalize each patch by shifting and scaling the intensity values to a range of  $[0, 1]$ .

# Two datasets

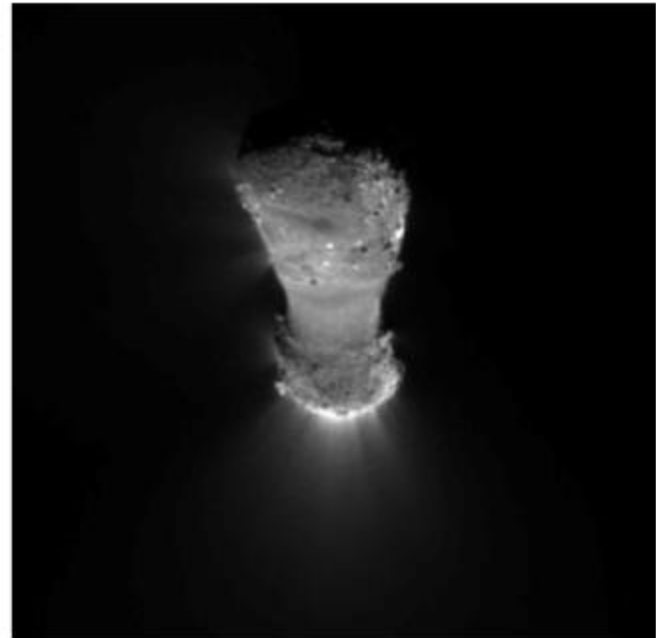
## Tempel 1

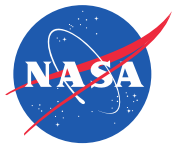
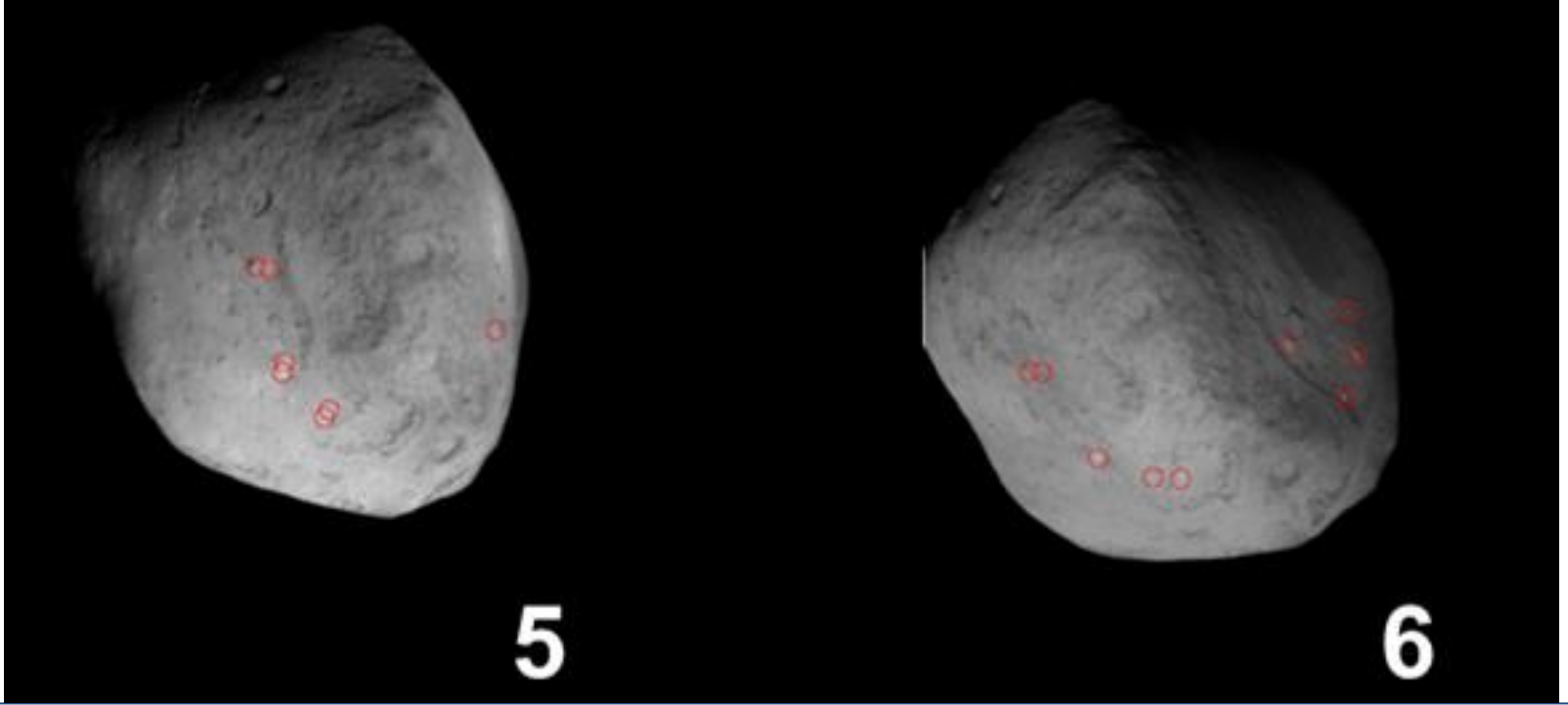
72 Frames, subtle targets



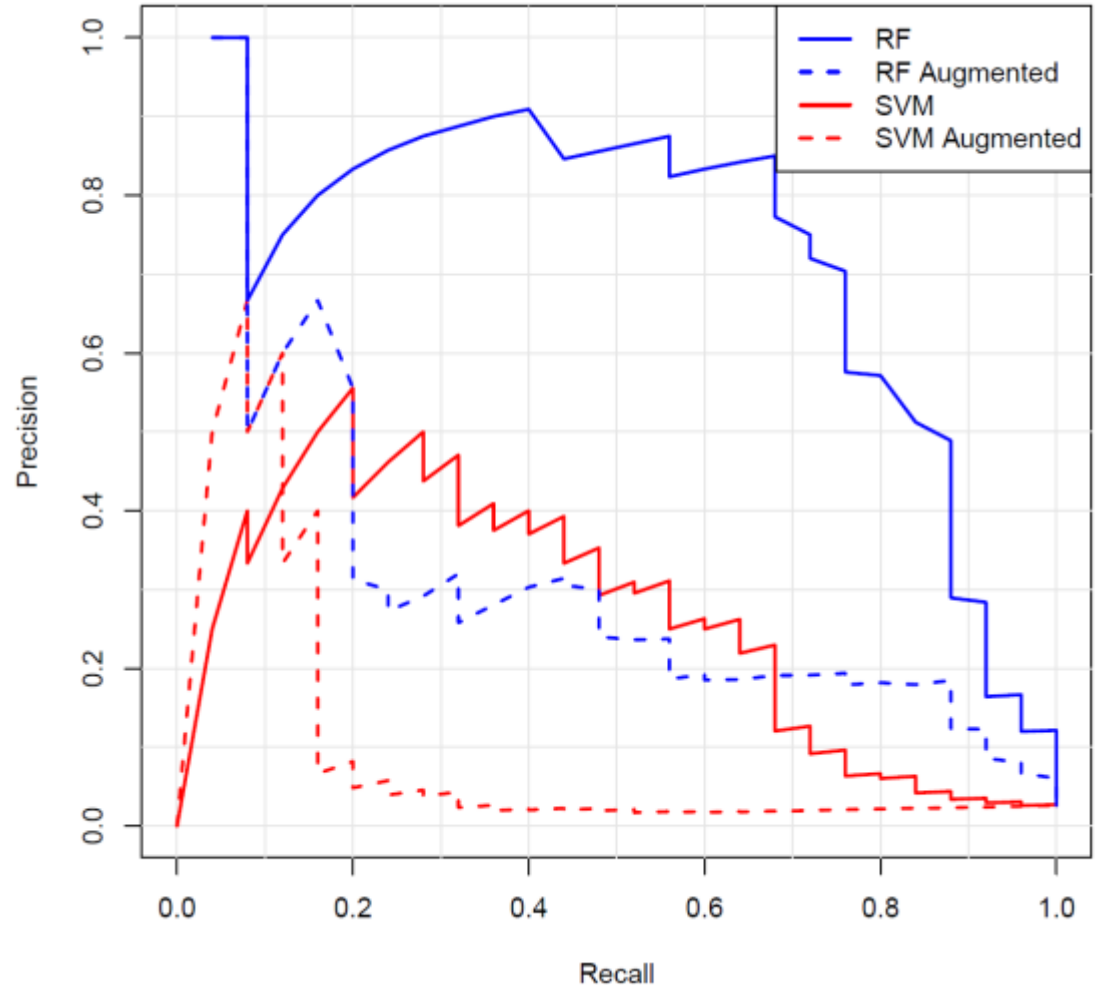
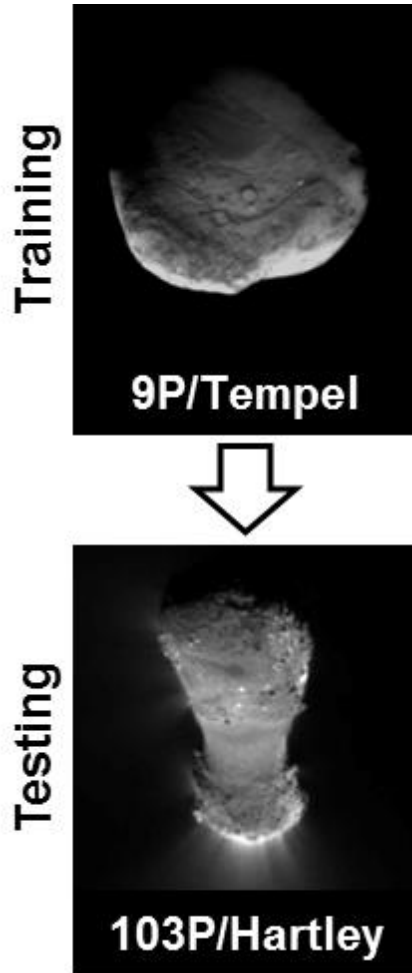
## Hartley 2

47 Frames, obvious targets

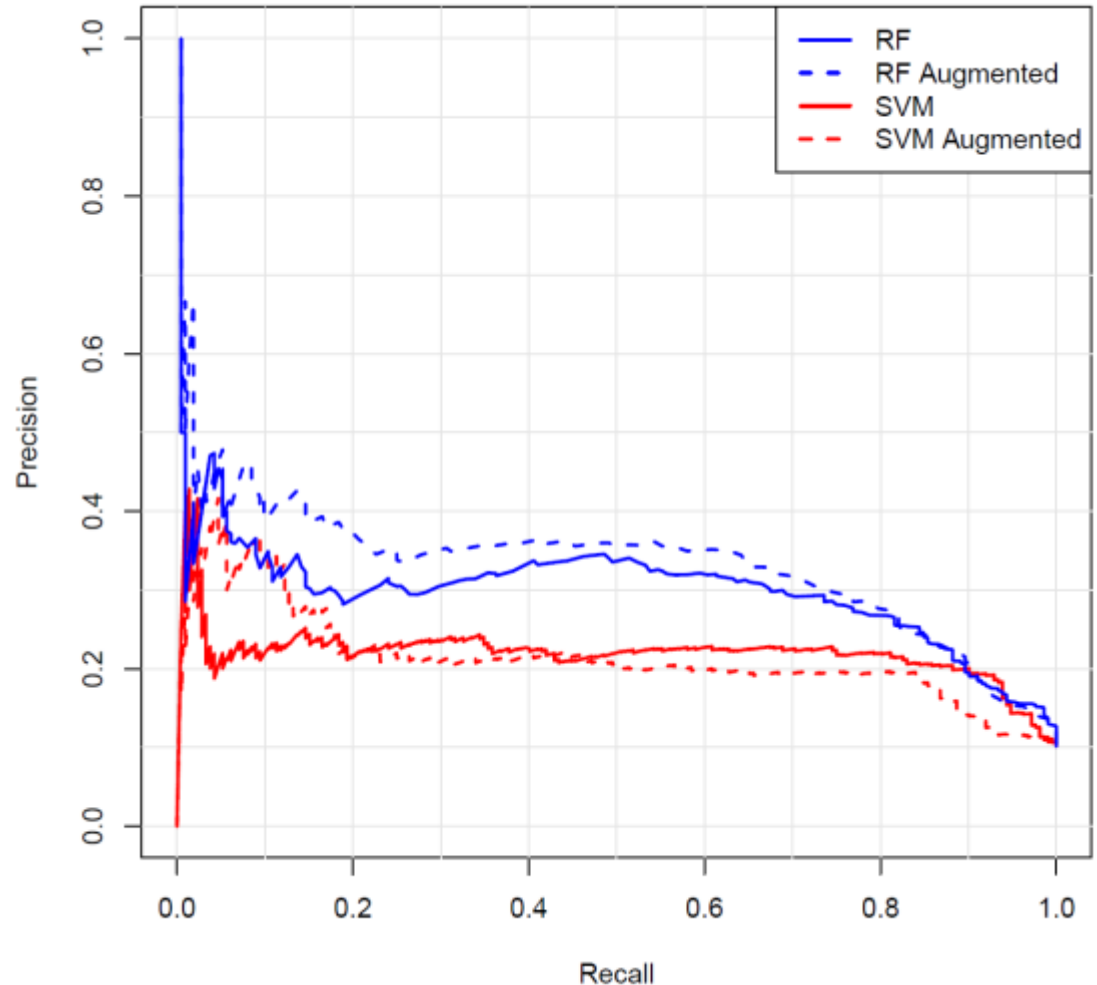
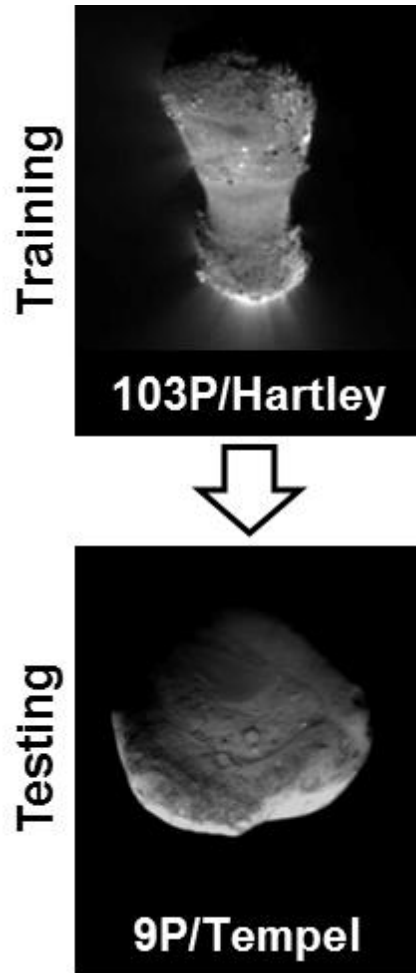




# Performance generalization (hard target -> easy target)



# Performance generalization (easy target -> hard target)



# Martian Scene Understanding

